

Department of Mathematics  
 Institut Teknologi Sepuluh Nopember  
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<b>Course</b>	<b>Course Name</b> : <b>Optimum Estimation</b>
	<b>Course Code</b> : <b>KM184816</b>
	<b>Credit</b> : <b>2</b>
	<b>Semester</b> : <b>8</b>

<b>Description of Course</b>	
This course examines classical estimates, deterministic observers, stochastic observers (estimation of stochastic dynamic systems), their formation and application for linear stochastic dynamic problems.	
<b>Learning Outcome</b>	
PLO 3	[C4] Students are able to analyze simple and practical problems in at least one field of analysis, algebra, modeling, system optimizations and computing sciences
PLO 4	[C5] Students are able to work on a simple and clearly defined scientific task and explain the results, both written and verbally either on the area of pure mathematics or applied mathematics or computing sciences
<b>Course Learning Outcome</b>	
1. Able to understand the problem of dynamic system estimation, know the methods of estimation both classical and modern and able to apply it appropriately 2. Able to analyze natural phenomena; identify the Mathematics model, estimate the variables by forming a good computer programming algorithm 3. Able to cooperate in presenting small topics related to optimum estimation in both written and oral form	
<b>Main Subject</b>	

Classical estimation theory, deterministic observer, stochastic observer, Kalman filter, Applied Kalman filter, Color Noise.
<b>Prerequisites</b>
Elementary Linear Algebra Ordinary Differential Equations
<b>Reference</b>
<ol style="list-style-type: none"> <li>1. Phil Kim, Lynn Huh, “Kalman Filter for Beginners : with MATLAB Examples”, A-JIN Publishing Company, 2010</li> <li>2. Dan Simon, “Optimal State Optimization”, John Wiley and Son, 2006</li> </ol>
<b>Supporting Reference</b>
<ol style="list-style-type: none"> <li>1. Lewis, F., “Optimal Estimation”, John Wiley &amp; Sons, Inc, 1986.</li> <li>2. Grewal, Mohinder, S., ”Kalman Filtering Theory and Practise Using MATLAB”, John Wiley &amp; Sons, Inc., 2008</li> </ol>